

DYNAMICS OF THE LINEAR PNEUMATIC ACTUATOR COMPUTER SIMULATION

| SYMBOL | NAME | UNIT | VALUE |
|----------------|------------------------------------|-------------------|----------------------|
| D | piston diameter | [m] | 0.063 |
| d | piston rod diameter | [m] | 0.025 |
| S | piston stroke | [m] | 0.100 |
| m | mass load | [kg] | parameter |
| F | force load | [N] | parameter |
| f | inlet area = outlet area | [m ²] | parameter |
| μ ₁ | inlet flow coefficient (1) | [-] | parameter |
| μ ₂ | outlet flow coefficient (2) | [-] | parameter |
| p _Z | supply pressure | [Pa] | parameter |
| p _a | ambient pressure | [Pa] | 100000 |
| p ₁ | pressure in the inlet chamber (1) | [Pa] | result of simulation |
| p ₂ | pressure in the outlet chamber (2) | [Pa] | result of simulation |
| s | piston position | [m] | result of simulation |
| v | piston velocity | [m/s] | result of simulation |
| t | time line | [s] | result of simulation |

MASS AIR-FLOW MODEL St. Venant-Wantzel

$$\dot{m} = \mu \cdot f \cdot p_A \cdot \sqrt{\frac{\kappa}{R \cdot T_0}} \cdot \sqrt{\frac{2}{\kappa - 1}} \cdot \Phi(\varepsilon) \quad \varepsilon = \frac{p_B}{p_A} \quad \Phi(\varepsilon) = \begin{cases} \sqrt{\frac{2}{\varepsilon^{\frac{2}{\kappa}} - \varepsilon^{\frac{\kappa+1}{\kappa}}}} & \text{for } 0.52828 < \varepsilon \leq 1 \\ 0.25880 & \text{for } 0 < \varepsilon \leq 0.52828 \end{cases}$$

for the inlet chamber: μ = μ₁ p_A = p_Z p_B = p₁

for the outlet chamber: μ = μ₂ p_A = p₂ p_B = p_a