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Determination of the Theoretical and Actual Working Volume of a Hydraulic Motor—Part II (The Method Based on the Characteristics of Effective Absorbency of the Motor)

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Abstract: In this article, the second method of determination of the theoretical and actual working volume of a hydraulic motor is described. The proposed new method is based on the characteristics of effective absorbency of the motor. The effective absorbency has been defined as the ratio of flow rate in a motor to the rotational speed of the motor's shaft. It has been shown that the effective absorbency is a nonlinear function of the rotational speed and nonlinear function of the pressure drop in the motor's working chambers. Furthermore, it has been proven that the actual working volume of a motor is a function of a third degree of pressure drop in the motor's working chamber. The actual working volume should be taken to assess the mechanical and volumetric energy losses in the motor. Furthermore, the influence of the flowmeter location in the measurement system and the compressibility of liquid on the result of the theoretical and actual working volume calculation was also taken into account and is described in this article. The differences in the assessment of the volumetric efficiency assuming the theoretical and actual working volume was also shown.

Keywords: hydraulic motor; effective absorbency; theoretical working volume; actual working volume; volumetric efficiency; mechanical efficiency



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1. Introduction

For users and designers of a hydraulic system, the volumetric and pressure-mechanical efficiency of the hydraulic positive displacement machine (motor or pump) is very important [1–6]. So far, these efficiencies are calculated based on the theoretical working volume q_t . The theoretical working volume q_t is a parameter that corresponds to the volume of liquid flowing without energy losses through the positive displacement machine during one full rotation of the shaft. The q_t is determined from experimental data. The value of q_t is constant in the whole range of the rotational speed n and the pressure drop Δp in a positive displacement machine [7–14].

It happens that the geometric working volume q_g is used instead of the q_t to calculate the energy losses in positive displacement machines. The q_g is calculated from geometrical dimensions of the working mechanism using special mathematical formulas which are different for various types of positive displacement machines [15]. The theoretical working volume q_t does not have to be equal to the geometrical working volume q_g and is usually not equal. The differences can be up to several percent [7,8,15]. The main reasons for these differences are:

- Looseness in the working mechanism,
- errors in the manufacturing of the components,
- assembly errors,
- changes in ambient temperature,
- changes in working liquid temperature, etc.

If the q_t corresponds to the volume of liquid flowing without energy losses through the motor during one full revolution of the motor shaft, then the q_t should be determined

by taking into consideration the pressure drop Δp_i in the working mechanism and the liquid compressibility β . If the liquid compressibility β is taken into account, then the location of a flow meter in the measuring system is of great important [12]. However, in practice, it is assumed that the pressure drop Δp in a motor is equal to the pressure drop Δp_i in the motor working chambers, and the liquid compressibility β is neglected [7,8,13,14].

In a loaded hydraulic motor, the working chambers are resiliently deformed (due to the pressure difference Δp_i). The working chamber under the pressure will have a bigger volume. Then, the working volume can differ from the geometric working volume q_g [8,12]. The working volume under the pressure difference Δp_i was called the actual working volume q_r [12]. Therefore, q_r is a function of the pressure drop Δp_i . It will be better to assume q_r instead of q_t and q_g to assess the losses in a hydraulic motor. Furthermore, in [12], it was shown that q_t and q_r should be determined by taking into account the liquid compressibility β . The precision determination q_r allows us to more precisely assess energetic losses and more precisely assess the clearances in the hydraulic motor working mechanism.

So far, there have been only a few publications on the methodology of determination of the theoretical working volume q_t of a displacement machine. The first method was described by Wilson in 1950 [16] and Schlosser and Hilbrands in 1963 [9–11]. This method was corrected and described by Toet in 1970 [13] and in 2019 [14], and also by Balawender in 1974 [8]. These authors described in their publications the method of determining the q_t based on the characteristics ($Q = f(n)_{\Delta p = const.}$) of flow rate Q in a motor as a function of rotational speed n at constant pressure drop Δp in this motor. The Toet and Balawender method have been referred in literature, like in [17–20].

The latest article on the methodology of determination the theoretical working volume was published in 2020 [12]. In this publication, the influence of liquid compressibility β and the influence of pressure drop Δp_{ich} in the motor internal channels on the q_t are described.

The second method of determining the q_t was proposed by Balawender [8]. This method is based on the characteristics $q_e = f(n^{-1})_{\Delta p = const.}$ of effective absorbency q_e as a function of rotational speed n at constant pressure drop Δp in the motor. Thus, the influence of pressure drop in the motor internal channel and liquid compressibility β were neglected.

According to ISO 8426, the theoretical working volume q_t is defined as a ratio of flow rate increment ΔQ to the corresponding rotational speed increment Δn [21]. The method according to ISO standard is the simplest of all the known methods and gives an inaccurate result.

There were also attempts to calculate the q_t by analyzing the flow rate for a single pump chamber [22]. However, this method becomes problematic to use in practice.

For this purpose, in the following sections are described:

- (a). Known methods for determining the theoretical working volume q_t ;
- (b). the proposed new method of determining the theoretical q_t and actual working volume q_r based on the characteristics $q_e = f(n)_{\Delta p_i = const.}$ (taking into account the compressibility β of liquid and the pressure drop Δp_{ich} in the internal channel of a motor);
- (c). the practical implementation of the proposed method;
- (d). the experimental tests of the hydraulic satellite motor for confirming the correctness of the proposed new method;
- (e). comparing the result of new method with the result of Balawender's method.

2. The Analysis of Flow Rate in a Hydraulic Motor

In order to determine the theoretical working volume q_t of the motor, it is necessary to measure and analyze the flow rate in this motor. Balawender recommends using two flow meters for this—one located in the inflow line of the motor and second in the outflow line (Figure 1) [7,8], whereas Toet indicates only one flowmeter located in the inflow line of the motor [13,14].

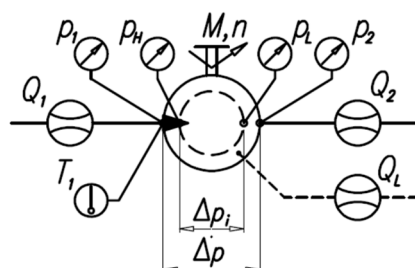


Figure 1. Parameters measured in a hydraulic motor: Q_1 , Q_2 and Q_L —flowrate, p_1 and p_2 —pressure in the inflow and outflow port, respectively, p_H and p_L —pressure in the high-pressure and low-pressure working chamber respectively, M —load (torque), n —rotational speed, T_1 —temperature, Δp —pressure drop in the motor, Δp_i —pressure drop in the motor working chambers.

2.1. Balawender’s Model

The flow rate in a hydraulic motor is described by the following formulas [7,8]:

$$Q_1 = Q_g + Q_u + Q_k + Q_{C1} + \underbrace{Q_{Li} - Q_{Le1}}_{Q_{L1}} \tag{1}$$

$$Q_2 = Q_g + Q_u + Q_k + Q_{C2} + \underbrace{Q_{Li} - Q_{Le2}}_{Q_{L2}} \tag{2}$$

where [7,8,12]:

- Q_g, Q_u, Q_k, Q_C —the components of the flow rate Q linearly dependent on the geometric volume q_g , the pressure drop Δp , and rotational speed n ;
- Q_{Li} —the internal leakage (from the high-pressure working chambers to the low-pressure working chambers):
- Q_{Le} —the external leakage linearly dependent on the theoretical working volume q_t and the pressure drop Δp (leakage from the working chambers on the outside of the motor—leakage from the motor body by the third hose):

$$Q_{Le1} + Q_{Le2} = Q_{Le} \tag{3}$$

$$Q_{Le1} \approx Q_{Le2} \approx 0.5 \cdot Q_{Le} \tag{4}$$

2.2. Sliwinski’s Model

The Balawender’s model of flow rate in a hydraulic motor is a general model. This model does not take into account the construction parameters of the motor. In this way, this model can try to adapt to any type of hydraulic motor, which is his advantage. On the other hand, the small accuracy is a disadvantage of this model. However, Sliwinski recommends using the model of flow rate in the motor based on analysis of construction and analysis of phenomena in the motor. Therefore, the type of motor and its construction is important. In this way, the basis for development of the model of flow rate in the motor is development of the model of volumetric losses in this motor. The mathematical model of volumetric losses, dedicated to the satellite motor (described in Section 6.1), is following [23,24]:

$$Q_L = \Delta Q_L + Q_{Lfg} + Q_C + Q_{Le} \tag{5}$$

where:

- Q_{Lfg} —flow rate in flat clearances of working mechanism [24,25]:

$$Q_{Lfg} = A_1 \cdot m^{\left(\frac{1-\beta}{2-\beta}\right)} \cdot \left(\frac{1}{v}\right)^{\left(\frac{\beta}{2-\beta}\right)} \cdot \left(\frac{2 \cdot h^3}{K \cdot A_2 \cdot \rho}\right)^{\left(\frac{1}{2-\beta}\right)} \cdot \Delta p_i^{\left(\frac{1}{2-\beta}\right)} \tag{6}$$

- Q_C —the flow rate in commutation unit clearances [24,26]:

$$Q_C = C_1 \cdot (D_o \cdot h_s)^{C_2} \cdot \left(\frac{1}{\rho \cdot \nu^{C_3}} \right)^\gamma \cdot \Delta p_i^\gamma \quad (7)$$

- ΔQ_L —the component of volumetric losses depends on the pressure drop Δp_i in the working chambers and rotational speed n of the motor [23,24]:

$$\Delta Q_L = \Delta q_L \cdot n \quad (8)$$

where:

$$\Delta q_L = \left(C_q \cdot \Delta p_i + \frac{C_{id}}{n^{0.5}} \right) \cdot m^2 \cdot H \quad (9)$$

- Q_{Le} —external leakage;
- $C_1, C_2, C_3, C_q, C_{id}, A_1, A_2, K$, and γ —coefficients;
- β —the degree of laminarity of the flow;
- ν —kinematic viscosity of liquid;
- m —teeth module;
- h —equivalent axial clearances of the rotor and satellites;
- h_s —axial clearance of the satellites;
- H —height of the working mechanism (equal to height of curvature);
- D_o —the diameter of inlet and outlet holes in the commutation plate.

The flow rate Q in the motor is:

$$Q = Q_t + Q_L \quad (10)$$

where Q_t is the theoretical flow rate in the motor:

$$Q_t = q_t \cdot n \quad (11)$$

If the influence of liquid compressibility β on the flow rate measurement result is omitted, then:

$$Q = Q_1 = Q_2 + Q_{Le} \quad (12)$$

If $Q_{Le} = 0$ then:

$$Q = Q_1 = Q_2 \quad (13)$$

3. The Pressure Drop in the Motor Working Chambers

The pressure difference Δp_i in the motor working chambers has an influence on the volumetric losses in the motor—as indicated above. This Δp_i is also taken into account during the determination of the theoretical working volume q_t of a motor. However, direct measurements of this pressure are very difficult or impossible. It is much easier to determine the Δp_i by measuring the pressure drop in Δp_{ich} in the internal channel of the motor. Then [12,24,27]:

$$\Delta p_i = \Delta p - \Delta p_{ich} \quad (14)$$

In most hydraulic motors, the inflow and outflow internal channels have the same shape and dimensions. Then the pressure drop Δp_{ich} can be calculated according to the formula [12,24,27]:

$$\Delta p_{ich} = 2 \cdot (p_1 - p_H) \quad (15)$$

The methodology of determination of the pressure drop Δp_{ich} in the internal channel of a motor is widely described in [24,27].

4. Known Method to Determine the Theoretical Working Volume

4.1. Balawender's and Toet's Method—Based on Characteristics $Q = f(n)$

Balawender and Toet claim that the flow rate Q (Q_1 or Q_2) in a hydraulic motor is described by a linear function [7,8,12,14]:

$$Q_{i,(\Delta p_i=\text{const})} = A_i \cdot n + B_i \quad (16)$$

where:

$$A_i = \lim_{\Delta p_i \rightarrow 0} \left(\frac{\partial Q_i}{\partial n} \right)_{(\Delta p_i)} \approx \lim_{\Delta p \rightarrow 0} \left(\frac{\partial Q_i}{\partial n} \right)_{(\Delta p)} \quad (17)$$

$$B_{i(\Delta p_i=\text{const})} = Q_{Li,i} + Q_{Le,i} \quad (18)$$

Balawender suggests testing the motor in the range of speed $n_{max} \leq 3n_{min}$. The n_{min} is the minimum speed at which the motor can work stably. The n_{max} is the maximum speed for which the assumption $\Delta p_i \approx \Delta p$ is true [7,8,12]. If $\Delta p_i \approx \Delta p$, then Equations (16) and (17) take the form:

$$Q_{i,(\Delta p=\text{const})} = A_i \cdot n + B_i \quad (19)$$

$$B_{i(\Delta p=\text{const})} = Q_{Li,i} + Q_{Le,i} \quad (20)$$

The flow rate characteristics $Q_1 = f(n)_{\Delta p=\text{const.}}$ are shown in 0 (Figure 2).

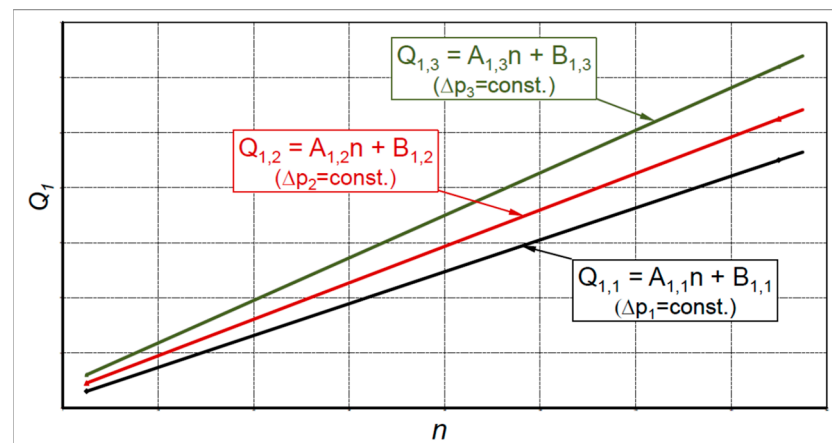


Figure 2. Flow rate Q_1 vs. rotational speed n [7,8,12,14]. Similar characteristics are obtained for Q_2 .

According to Balawender, between A and Δp is the following relationship (Figure 3) [7,8]:

$$A = a \cdot \Delta p + q_a \quad (21)$$

Similarly between B and Δp is (Figure 3) [7,8]:

$$B = q_{Le} = b \cdot \Delta p + q_{Le,0} \quad (22)$$

The theoretical working volume is described as [7,8,12]:

$$q_{t1} = \lim_{\Delta p \rightarrow 0} A_1(\Delta p) - \frac{1}{2} \cdot \lim_{\Delta p \rightarrow 0} q_{Le}(\Delta p) \quad (23)$$

and

$$q_{t2} = \lim_{\Delta p \rightarrow 0} A_2(\Delta p) + \frac{1}{2} \cdot \lim_{\Delta p \rightarrow 0} q_{Le}(\Delta p) \quad (24)$$

In practice, only one flowmeter is applied in measuring system. Then $q_t = q_{t1}$ or $q_t = q_{t2}$.

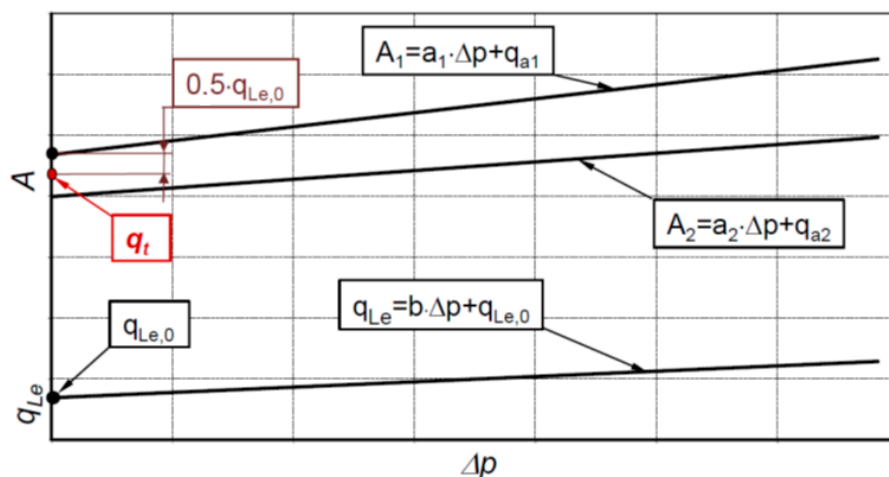


Figure 3. Linear relationship between working volume A and leakage q_{Le} and pressure difference Δp [7,8,12].

4.2. The Influence of Working Pressure on Working Volume

According to Balawender and Toet, the geometric working volume q_g is a linear function of pressure [7,8,14]:

$$q_{g(\Delta p_i)} = q_{g(\Delta p_i=0)} \cdot (1 \pm K_6 \cdot \Delta p_i) \tag{25}$$

This is a simplification, of course. Similarly, Sliwinski assumed that the increase in the positive displacement machine’s working volume is a function of pressure drop in the motor working chambers and can be described by the Formula (9).

The influence of working pressure on the working volume was also noticed by Osiecki during the test of prototype of axial piston pump with cam-driven unit [6]. With increasing the load of the pump, the working volume of the pump also increased. Thus, it can be seen that the adoption of the theoretical working volume q_t can introduce a significant error in the evaluation of the losses in displacement machines. Therefore, in [12], it has been shown that is not advisable to assume q_t for the assessment of losses in the motor in the whole range of its load. However, it is better and more precise to use the actual working volume q_r defined as [12]:

$$q_r = q_{g(\Delta p_i=0)} \underbrace{\pm f(\Delta p_i^3) \pm f(\Delta p_i^2) \pm f(\Delta p_i)}_{\Delta q_{g(\Delta p_i)}} \tag{26}$$

4.3. Balawender’s Method—Based on Characteristics $q_e = f(n)_{\Delta p=const.}$

The effective absorbency q_e of the motor is defined as [7,8]:

$$q_e = \frac{Q}{n} \tag{27}$$

In relations to the flowmeters Q_1 and Q_2 (Figure 1):

$$q_{e1} = \frac{Q_1}{n} \tag{28}$$

$$q_{e2} = \frac{Q_2}{n} \tag{29}$$

In his considerations, Balawender omits the pressure drop Δp_{ich} in internal channels of the motor and assumes: $\Delta p_i \approx \Delta p$.

Therefore, taking into consideration the Formulas (1) and (2) [7,8]:

$$q_{e1} = \underbrace{q_g + q_u + q_k + q_{C1}}_{q_{w1}} + \underbrace{\frac{Q_{L1}}{n}}_{q_{Le1}} \tag{30}$$

$$q_{e2} = \underbrace{q_g + q_u + q_k + q_{C2}}_{q_{w2}} + \underbrace{\frac{Q_{L2}}{n}}_{q_{Le2}} \tag{31}$$

According to Balawender, the q_e is the linear function of $1/n$ (Figure 4).

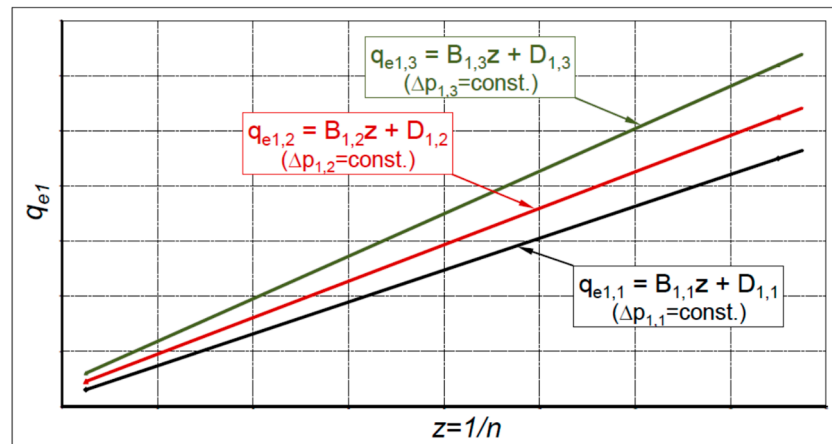


Figure 4. Linear interrelationship between q_{e1} and $1/n$ for different constant Δp in the motor for flowmeter Q_1 (Figure 1) [8].

If the rotational speed n increases, then the leakage Q_L has a smaller share in the effective flow rate in the motor. In effect [8]:

$$\lim_{n \rightarrow \infty} (q_{e1})_{(\Delta p)} = (q_{w1} + q_{Le1})_{(\Delta p)} \approx (q_{w1})_{(\Delta p)} - 0.5 \cdot q_{Le1} = D_1 \tag{32}$$

$$\lim_{n \rightarrow \infty} (q_{e2})_{(\Delta p)} = (q_{w2} - q_{Le2})_{(\Delta p)} \approx (q_{w2})_{(\Delta p)} + 0.5 \cdot q_{Le2} = D_2 \tag{33}$$

According to Balawender, the q_{w1} and q_{w2} are the linear function of Δp (Figure 5).

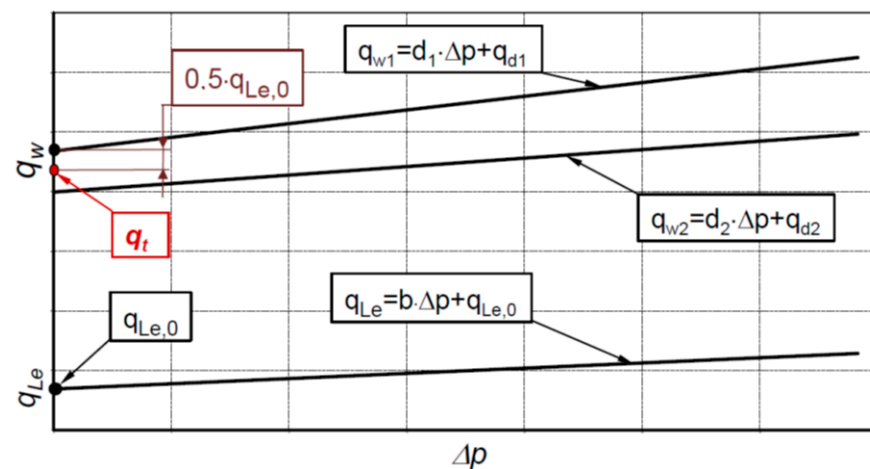


Figure 5. Linear relationship between working volume q_w and leakage q_{Le} and pressure drop [7,8].

Similarly, if the Δp decreases, then the leakages Q_L also decreases. Then the q_t is calculated from the following formulas [6,8]:

$$\lim_{\Delta p \rightarrow 0} (D_1) = q_g + q_u - 0.5 \cdot q_{Le0} = q_{t1} \quad (34)$$

$$\lim_{\Delta p \rightarrow 0} (D_2) = q_g + q_u + 0.5 \cdot q_{Le0} = q_{t2} \quad (35)$$

In practice, only one flowmeter is applied in the measuring system. Then $q_t = q_{t1}$ or $q_t = q_{t2}$.

4.4. The Influence of the Flow Meter Location in the Measurement System on the Flow Rate in the Hydraulic Motor

4.4.1. Toet's Method

Toet recommends placing a flow meter in the inlet line to a hydraulic motor. Then the flow meter measures total flow rate, including the external leakage. However, if the flow meter is located in the low-pressure line, the influence of the liquid compressibility on the flow rate should be taken into account. Then [14]:

$$Q_{(p_1)} = Q_2 + \underbrace{q_{g(\Delta p=0, T_1)} \cdot K_3 \cdot \Delta p - K_4 \cdot (\Delta p)^2 + K_5 \cdot (\Delta p)^3 \cdot n}_{Q_c} \quad (36)$$

where K_1, K_2, K_3, K_4, K_5 are constants. That is, the effect of liquid compressibility is related to the geometric working volume q_g . Furthermore, the influence of liquid compressibility on the leakage Q_L is neglected. Therefore, this assumption introduces some error in calculations of the theoretical working volume q_t .

4.4.2. Balawender's Method

Balawender recommends locating the flow meter in two places of hydraulic circuit. The first place is the high-pressure line of the motor. Then $Q_{(p_1)} \approx Q_1$ [8]. The second place is the low-pressure line of the motor. For this location of flow meter [8]:

$$Q_{(p_1)} = \kappa \cdot Q_2 \quad (37)$$

where κ is the correction coefficient. For oil, for $t = 40^\circ \text{C}$, the value of the coefficient is [8]:

$$\kappa = 0.97 - 75 \cdot 10^{-5} \cdot \Delta p \quad (38)$$

and Δp is expressed in [MPa].

Finally, in a practical approach to determine the theoretical working volume, both Toet and Balawender simplify the problem, and the effect of the flow meter location in the measuring system is finally neglected.

4.4.3. Sliwinski's Method

The flow rate $Q_{(p_H)}$ related to the pressure p_H in the high-pressure working chamber is possible to calculate depending on the location of a flow meter in measuring system. Thus:

- (a). For the flow meter located in the high-pressure line to the motor (Figure 1), the flow rate is [12]:

$$Q_{1(p_H)} = Q_1 \cdot \left(1 + \int_{p_H}^{p_1} \frac{1}{K_{Z(p)}} \cdot \partial p \right) \quad (39)$$

- (b). For the flow meter located in the low-pressure line to the motor (Figure 1), the flow rate is:

$$Q_{2(p_H)} = Q_2 \cdot \left(1 - \int_{p_2}^{p_H} \frac{1}{K_{Z(p)}} \cdot \partial p \right) \quad (40)$$

where:

- $K_{Z(p)}$ —the tangential isentropic bulk modulus [28]:

$$K_{Z(p)} = \frac{e^{\left(\frac{p_0-p}{K}\right)} \cdot \left[1 + m \cdot \frac{p-p_0}{K}\right]^{\left(-\frac{1}{m}\right)} + \frac{X_o}{1-X_o} \cdot \left(\frac{p_0}{p}\right)^{\left(\frac{1}{n}\right)}}{e^{\left(\frac{p_0-p}{K}\right)} \cdot \left[1 + m \cdot \frac{p-p_0}{K}\right]^{\left(\frac{1-m}{m}\right)} + \frac{X_o}{n \cdot p_0 \cdot (1-X_o)} \cdot \left(\frac{p_0}{p}\right)^{\left(\frac{1+n}{n}\right)}} \quad (41)$$

- K —the bulk modulus of non-aerated oil at atmospheric pressure p_0 ;
- X_o —the amount of non-dissolved air in the oil at atmospheric pressure p_0 ;
- p —the absolute pressure;
- n —the polytrophic exponent;
- m —the coefficient of the influence of pressure p on the bulk modulus K .

5. New Method of Determining the Theoretical and Actual Working Volume Based on the Characteristics of Effective Absorbency of the Motor

In the above described Balawender's method of determining theoretical working volume, it is assumed that $\Delta p_i = \Delta p$. That is, the pressure drop Δp_{ich} in internal channels of a motor is omitted. This simplification can have the influence on the value of theoretical working volume q_t of the motor. Furthermore, Balawender assumed that the volumetric losses Q_L in a motor are linear function of rotational speed n (Section 2.1). Whereas, the analysis of volumetric losses in the motor, carried out by Sliwinski, show that these losses are a nonlinear function of speed n (Formula (9)). Furthermore, various researchers argue that the increase in working volume of a motor is a linear function of pressure drop in the motor (Formulas (9) and (25)) [7,8,13,14]. This is a simplification, of course. In fact, the motor's working chamber is a spatial element, and each of its dimensions changes linearly under the influence of pressure. Therefore, the change in working volume of a motor is a nonlinear function of the pressure drop Δp_{ich} in its working chamber.

In the below described new method of determining the theoretical working volume q_t , it is assumed:

- Δp_i instead Δp ;
- nonlinear dependence of volumetric losses Q_L on rotational speed n ;
- nonlinear dependence of increasing in working volume Δq on pressure drop Δp_i ;
- the compressibility β of the liquid, that is the measured flow rate is compensated to the pressure in the filled chamber of the motor (the location of flowmeter in the test stand is included).

5.1. The Increase in Working Volume

In publications [7,8,23,24] and in Section 2.2, it is written that the rotational speed n has an influence on the increase in volumetric losses Δq (Formulas (8) and (9)). This is because of the movement of working mechanism elements within the slack. This movement causes an additional increase in working volume. In effect, additional volumetric loss is created depending on the speed. Furthermore, the increase in working volume Δq is a nonlinear function of pressure drop Δp_i [23,24]. So, the increase in working volume Δq_g caused by the pressure drop Δp_i in the working chamber cannot be the reason of the volumetric losses in a motor. Therefore, Formula (9) is inaccurate, and instead of it, the following is proposed:

$$\Delta q = \Delta q_g + \Delta q_L \quad (42)$$

where:

$$\Delta q_g = m^2 \cdot H \cdot (C_{q1} \cdot \Delta p_i + C_{q2} \cdot \Delta p_i^2 + C_{q3} \cdot \Delta p_i^3) \quad (43)$$

$$\Delta q_L = \frac{C_{id}}{n^{0.5}} \cdot m^2 \cdot H \quad (44)$$

5.2. The Actual Working Volume of a Loaded Motor

In [12], it was shown that with a change in pressure drop Δp_i in working chambers the working volume also is in change according to formula:

$$q_r = q_t + \underbrace{\left(C_{q1} \cdot \Delta p_i + C_{q2} \cdot \Delta p_i^2 + C_{q3} \cdot \Delta p_i^3 \right)}_{\Delta q_g} \cdot m^2 \cdot H \quad (45)$$

The q_r was called the actual working volume. For $\Delta p_i = 0$ is $q_r = q_t$. The value of q_r is obtained experimentally. The determination of q_r is possible only when the component of flow rate Q_C (caused by liquid compressibility) is eliminated (see Section 4.4).

5.3. Flow Rate in a Motor

Taking into account Formula (45), the flow rate in a motor should be described by:

$$Q = \underbrace{q_r \cdot n}_{Q_r} + \underbrace{\Delta q_L \cdot n + Q_{Lfg} + Q_C + Q_{Le}}_{Q_L} \quad (46)$$

where Δq_L is described by Formula (44).

It can be assumed that the flow rate Q is a linear function of rotational speed n of a motor. The flow rate Q is measured by flowmeter and in this way Formulas (12) and (13) are applied.

5.4. The Effective Absorbency

The effective absorbency q_e of the motor should be calculated according to the following formulas:

$$q_{e1} = \frac{Q_1(p_H)}{n} \quad (47)$$

$$q_{e2} = \frac{Q_2(p_H)}{n} \quad (48)$$

Thus, after substitution (5), (8), (9), and (10) into (47) and (48), respectively, the following are obtained:

$$q_{e1} = q_t + \left(C_{q1} \cdot \Delta p_i + C_{q2} \cdot \Delta p_i^2 + C_{q3} \cdot \Delta p_i^3 \right) \cdot m^2 \cdot H + \frac{C_{id}}{n^{0.5}} \cdot m^2 \cdot H + \frac{Q_{Lfg} + Q_C + Q_{Le}}{n} \quad (49)$$

$$q_{e2} = q_t + \left(C_{q1} \cdot \Delta p_i + C_{q2} \cdot \Delta p_i^2 + C_{q3} \cdot \Delta p_i^3 \right) \cdot m^2 \cdot H + \frac{C_{id}}{n^{0.5}} \cdot m^2 \cdot H + \frac{Q_{Lfg} + Q_C}{n} \quad (50)$$

Therefore, the effective absorbency q_e is a linear function of Δp_i and nonlinear function of the inverse of rotational speed n of the motor. That is:

$$q_{e1} \text{ (or } q_{e2}) = f\left(\Delta p_i, n^{-0.5}\right) \quad (51)$$

In addition, it is worth noting that in the case of flow meter located in the motor outflow line the component Q_{Le} is omitted (because is not measured).

5.5. Theoretical Working Volume

If rotational speed n of a motor increases, then the share of leakages Q_L in the general balance of flow rate Q in the motor decreases. Therefore, the value of q_e , described by Formulas (49) and (50), strives to a certain value q_r , namely:

$$\lim_{n \rightarrow \infty} (q_{e1})_{(\Delta p_i)} = q_{r1} = q_{t1} + \Delta q_{g1} \quad (52)$$

$$\lim_{n \rightarrow \infty} (q_{e2})_{(\Delta p_i)} = q_{r2} = q_{t2} + \Delta q_{g2} \quad (53)$$

If $\Delta p_i = 0$, then $\Delta q_g = 0$. Thus, the theoretical working volume can be defined as follows:

$$\lim_{\Delta p_i \rightarrow 0} (q_{r1}) = q_{t1} \quad (54)$$

$$\lim_{\Delta p_i \rightarrow 0} (q_{r2}) = q_{t2} \quad (55)$$

If the measurement of flow rate Q_1 and Q_2 are made using flow meters of the same type and class and the compressibility of liquid is taken into account, then the theoretical working volumes (expressed by Formulas (54) and (55)) should have the same value:

$$q_{t1} = q_{t2} = q_t \quad (56)$$

In practice, only one flowmeter is applied in measuring system. Then $q_t = q_{t1}$ or $q_t = q_{t2}$.

5.6. Practical Implementation of the New Method

The practical implementation of the methodology of determining the theoretical working volume q_t based on the characteristics of $Q = f(n)_{\Delta p_i = \text{const.}}$ were described in [12]. In this place it is worth once again present this implementation and adjust it to the proposed new method. So, in order to determine the theoretical q_t and actual working volume q_r it is necessary [12]:

- (a). To measure the flow Q_1 or Q_2 at a constant inlet temperature T_1 and a constant pressure drop Δp for several values of n (no less than five). The measurement has to be taken once again using at least five different pressure drops Δp ;
- (b). to determine the pressure drop Δp_{ich} in the internal channel of the motor;
- (c). to calculate the pressure drop Δp_i in the working chamber of the motor for data from item (a) and item (b);
- (d). if the flow meter is located in the low-pressure line, the influence of the liquid compressibility should be taken into account, and the flow rate $Q_{(pH)}$ corresponding to the value of high-pressure p_H in the working chamber should be calculated;
- (e). to plot the characteristics of $q_e = f(1/n)_{\Delta p_i = \text{const.}}$ and calculate the q_r according to Formulas (52) or (53) for each Δp_i ;
- (f). to plot the characteristics of $q_r = f(\Delta p_i)$ and calculate the trend line of q_r with equation (equation in the form (45)). Finally, from the obtained the theoretical working volume q_t should be read.

6. Results of Experimental Research

6.1. Tested Motor

A prototype of a hydraulics satellite motor was selected for experimental tests. The construction of this motor is presented in Figure 6. The working mechanism of the satellite motor consists of internally toothed curvature C, externally toothed rotor R, and satellites S (Figure 7). The principle of operation of this working mechanism was widely described in other author's publications, especially in [23–27,29,30].

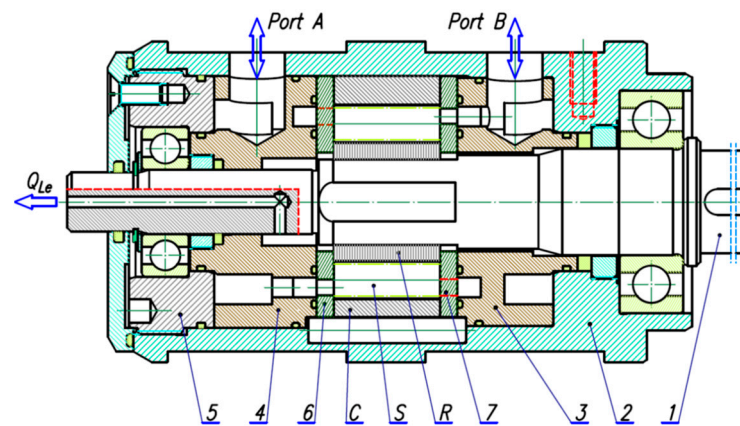


Figure 6. Hydraulic satellite motor [12,24]: C—curvature (stator); S—satellite; R—rotor; 1—shaft; 2—case; 3 and 4—inflow and outflow manifolds; 5—rear body; 6 and 7—distribution (compensation) plates.

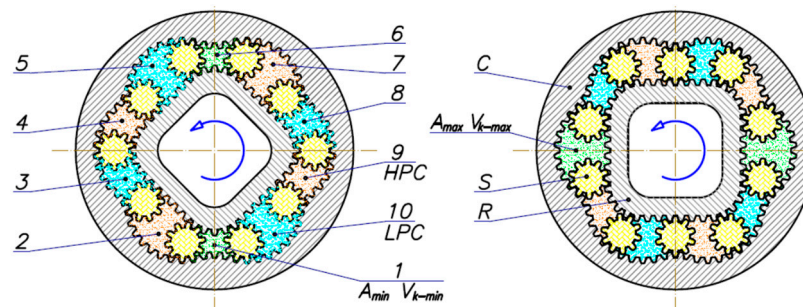


Figure 7. Satellite mechanism of type II [12,23–27,30]: C—curvature, R—rotor, S—satellite, 1÷10—working chambers, HPC—high pressure chambers, LPC—low pressure chambers, V_{k-min} —working chamber with minimum volume (dead chamber) and with minimum area A_{min} , V_{k-max} —working chamber with maximum volume and with maximum area A_{max} .

The number of filling and emptying cycles of the working chambers per one rotation of the shaft is the product of the number n_R of humps of the rotor and the number n_C of humps of the stator. Thus, 24 cycles correspond to one shaft revolution [12,24].

The geometric working volume q_g of the satellite mechanism depends on the number n_R of humps of the rotor and the number n_C of humps of the stator and is calculated according to the following formula [12,24]:

$$q_g = n_C \cdot n_R \cdot H \cdot (A_{max} - A_{min}) \quad (57)$$

The following geometrical parameters characterized the satellite motor [12]:

- The height of the working mechanism $H = 25$ mm;
- the minimum area of the working chamber $A_{min} = 26.11$ mm²;
- the maximum area of the working chamber $A_{max} = 83.51$ mm².

Thus, the geometric working volume of the satellite mechanism is $q_g = 34.44$ cm³/rev.

6.2. The Test Stand and Measuring Apparatus

The satellite motor was tested on a test stand with power recuperation. The diagram of the measurement system of this test stand is shown in Figure 8.

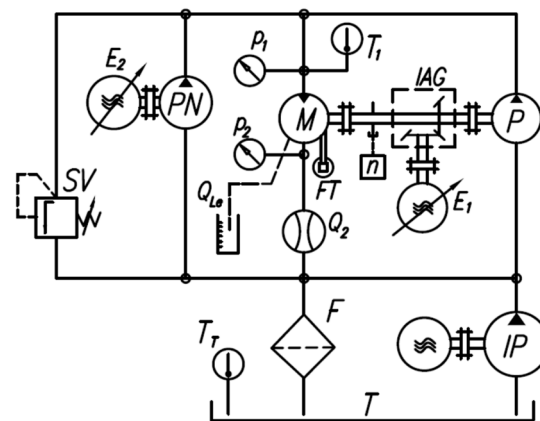


Figure 8. Diagram of the test stand measurement system [12,29]: P—pump, M—tested hydraulic motor, PN—pump for filling leaks in P and M, IP—impeller pump (pre-supply pump), SV—safety valve, F—filter, T—reservoir, IAG—intersecting axis gear, E₁ and E₂—electric motors with frequency converters, T₁, T_T—temperature sensors, Q₂—flowmeter, Q_{Le}—leakage measurement, FT—force transducer (torque measurement), n—inductive sensor (rotational speed measurement).

Parameters of the motor measured during the test were summarized in Table 1.

Table 1. Parameters of the tested motor.

Parameter	Device	Range	Class
Pressure p_1 (in the inflow port)	Strain gauge pressure transducer	0–10 MPa and 0–40 MPa	0.3
Pressure p_2 (in the outflow port)	Strain gauge pressure transducer	0–2.5 MPa	0.3
Flow rate Q (motor absorption)	Piston flowmeter (the flowmeter chamber volume 0.63 dm ³)	0–200 L/min	0.2
Torque M	Strain gauge force transducer mounted on the arm 0.5 m	0–100 N	0.1
Rotational speed n	inductive sensor	Accuracy of measurement ± 0.01 rpm	
temperature T_1 (in the inflow port)	RTD temperature sensor	Max. meas. error 0.5 °C	A

In order to determine the working volume of the motor with the smallest possible error, it is important to maintain the setting of speed n , pressure drop Δp , and liquid temperature T_1 with the least possible deviation. Thus [12]:

- For rotational speed n the deviation was ± 0.1 rpm;
- for the pressure drop Δp the deviation was ± 0.05 MPa;
- for the temperature in inflow port T_1 the deviation was ± 1.0 °C.

6.3. Working Liquid Parameters

The oil Total Azolla 46 was the working liquid during the satellite motor tests. The temperature in the inflow port of the motor $T_1 = 43$ °C which corresponds to the kinematic viscosity $\nu = 40$ cSt and oil density $\rho = 873$ kg/m³.

The characteristic of tangential isentropic bulk modulus $K_{Z(p)}$ of Total Azolla 46 oil is shown in Figure 9. The $K_{Z(p)}$ was calculated according to the Formula (41) for the data given in Table 2.

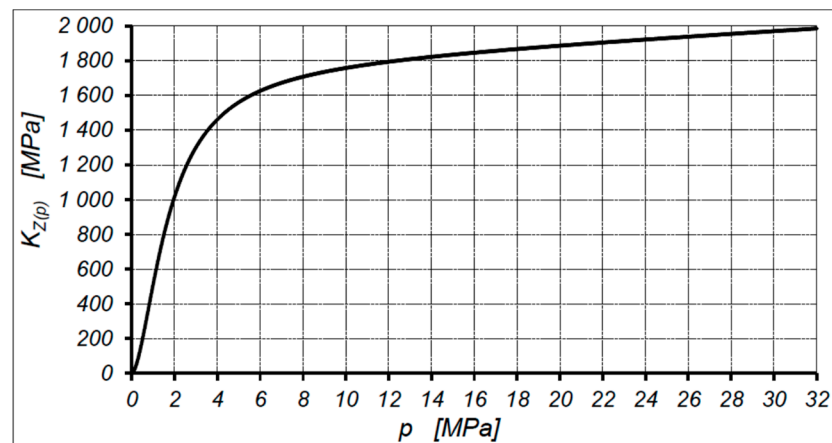


Figure 9. Characteristic $K_{Z(p)} = f(p)$ of oil Total Azolla 46 [12,28].

Table 2. Liquid parameters for calculation the $K_{Z(p)}$ [12,30].

Parameter	Value
K	1775 MPa
X_o	0.01
n	1.4
m	9.19
P_o	0.1 MPa

6.4. Pressure Drop in Motor Internal Channels

Refs. [24,27] precisely described the method of determining the pressure drop Δp_{ich} in a motor's internal channels. For the tested motor, the Δp_{ich} can be described by the following empirical formula [12]:

$$\Delta p_{ich} = 0.003224 \cdot Q_2^2 + 0.02183 \cdot Q_2 \quad (58)$$

where Q_2 in [L/min] and Δp_{ich} in [MPa].

6.5. Motor Output Flow Rate Characteristics

The satellite motor was tested in the range of rotational speed $n = 50 \div 1500$ rpm and in this speed range the characteristics $Q_2 = f(n)$ at $\Delta p = const.$ were determined (Figure 10). In order to maintain the clarity of the graphs the characteristics are shown only for two extreme pressure drops in the motor, that is, for $\Delta p = 2$ MPa and $\Delta p = 32$ MPa.

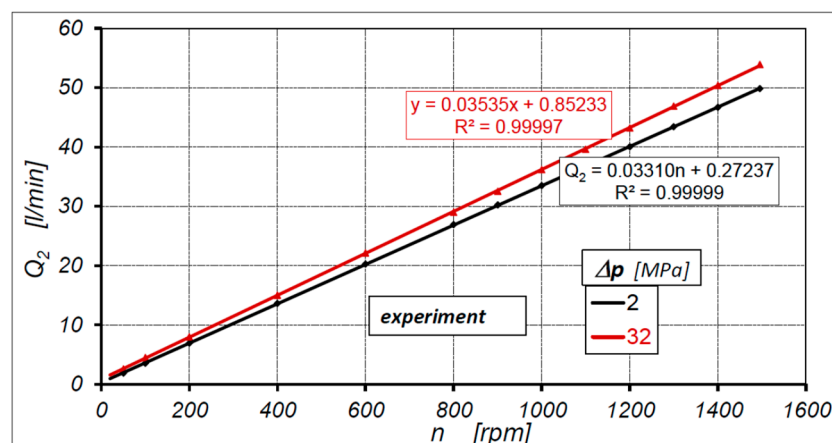


Figure 10. Characteristics of motor output flow rate Q_2 as a function of rotational speed n at $\Delta p = const.$ [12].

The results of the experiment show that the characteristics of flow rate Q_2 (at $\Delta p = \text{const.}$) are a linear function of rotational speed n , and they are compatible with theoretical characteristics presented in Figure 2. Therefore, the characteristics of Q_2 can be described by Equation (19), as shown in Figure 10.

The value of external leakage Q_{Le} in the tested motor is no more than 0.06 L/min in the whole range of the motor load [12]. Due to a very small value, the leakage Q_{Le} was omitted.

In Figure 11, the characteristics of output flow rate Q_2 at constant pressure drop Δp_i in working chambers (for $\Delta p_i = 2$ MPa and $\Delta p_i = 32$ MPa) are shown. The Δp_i was calculated according to Formulas (14) and (58) (that is was taken into account the pressure drop Δp_{ich} in the internal channels of the motor). The influence of liquid compressibility was omitted.

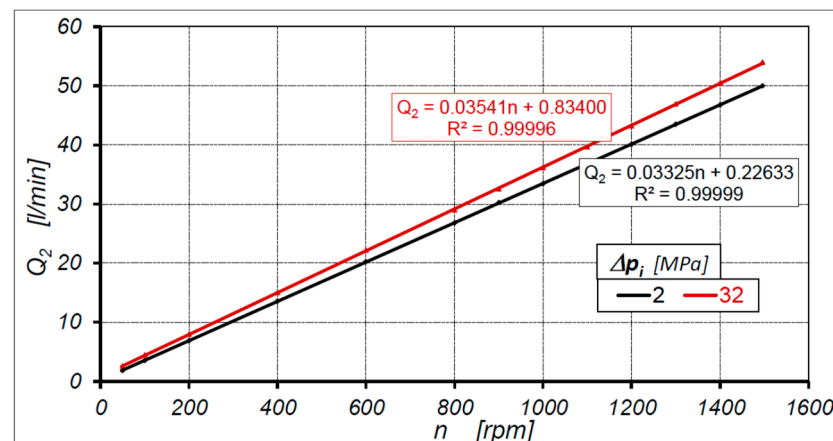


Figure 11. Characteristics of motor output flow rate Q_2 as a function of rotational speed n at $\Delta p_i = \text{const.}$ The influence of liquid compressibility is omitted [12].

The flow rate $Q_{(pH)}$ related to the pressure p_H in the high-pressure chamber of the motor was calculated (using the method described in Section 4.4.3—that is the liquid compressibility was taken into account) and shown in Figure 12 (for $\Delta p_i = 2$ MPa and $\Delta p_i = 32$ MPa).

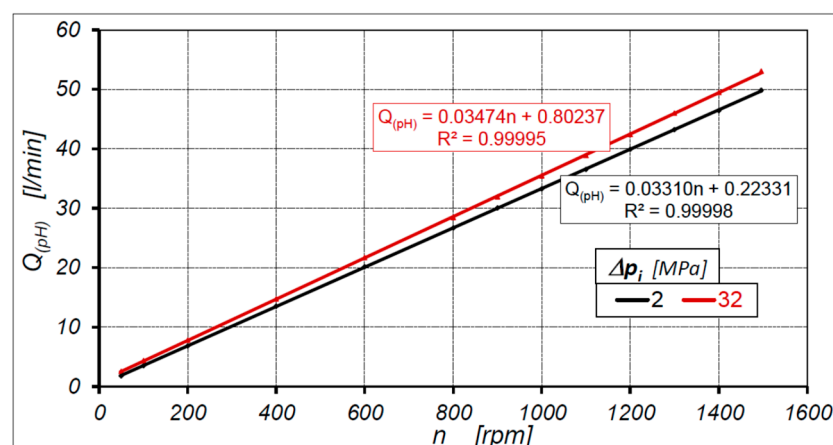


Figure 12. Characteristics of $Q_{(pH)} = f(n)$ at $\Delta p_i = \text{const.}$ related to the pressure in the high-pressure working chamber [12].

6.6. Theoretical Working Volume According to Balawender's Method

The characteristics of $q_e = f(n^{-1})$ determined according to Balawender's method are shown in Figure 13.

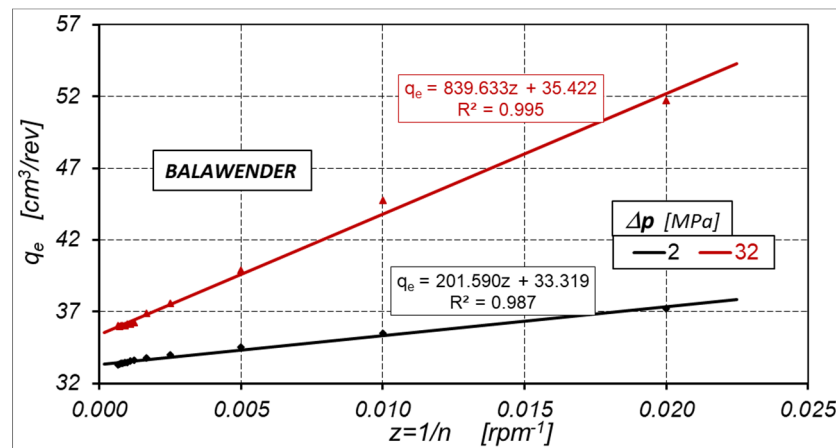


Figure 13. Characteristics of $q_e = f(n^{-1})$ at $\Delta p = \text{const.}$ —according to Balawender’s method.

According to the Balawender method, the theoretical working volume q_t of the satellite motor is $q_t = 33.312 \text{ cm}^3/\text{rev}$. (Figure 14).

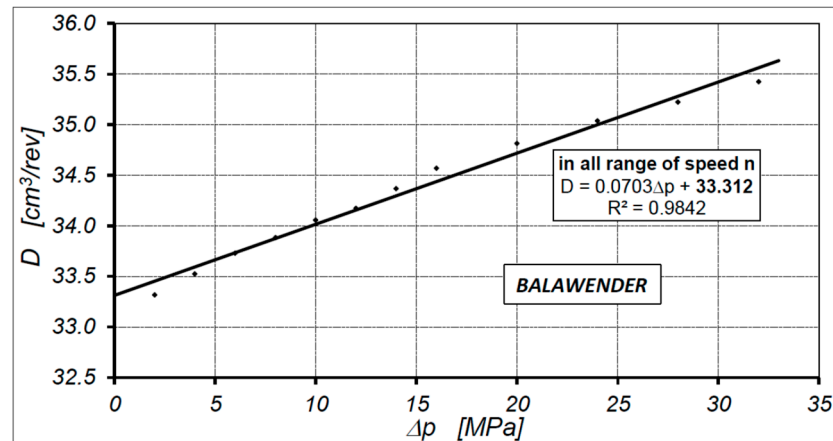


Figure 14. Characteristics of $D = f(\Delta p)$ (Balawender’s method).

6.7. Motor Theoretical Working Volume According to Proposed New Method

The characteristics of $q_e = f(n^{-0.5})$ determined according to the proposed new method are shown in Figure 15.

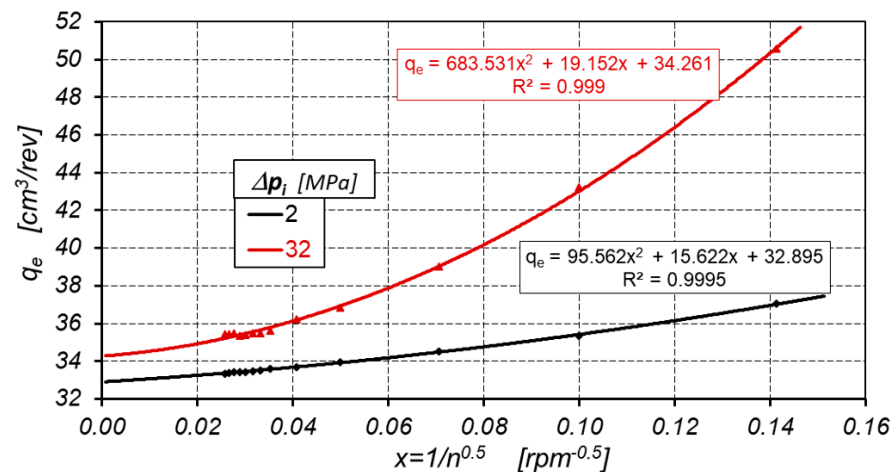


Figure 15. Characteristics $q_e = f(n^{-0.5})$ at $\Delta p = \text{const.}$ —according to the new method.

According to the new method, the theoretical working volume of the satellite motor is $q_t = 32.559 \text{ cm}^3/\text{rev}$. (Figure 16).

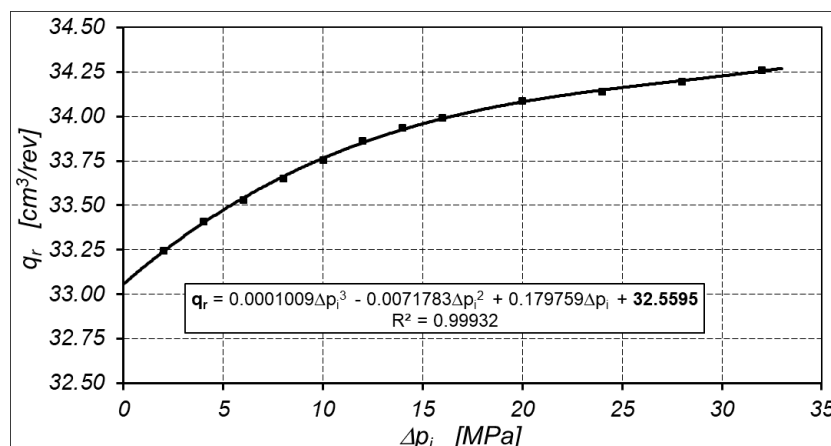


Figure 16. Characteristics of working volume q_r as a function of pressure drop Δp_i in the motor working chambers (according to the new method).

7. Discussion

The theoretical analysis indicates that the flow rate in a hydraulic motor is a linear function of rotational speed (see Equations (10), (11), and (46)). All experimental data (see characteristics $Q_2 = f(n)_{\Delta p = \text{const.}}$ in Figure 10, $Q_2 = f(n)_{\Delta p_i = \text{const.}}$ in Figure 11, and the characteristics of $Q_{(pH)} = f(n)_{\Delta p_i = \text{const.}}$ in Figure 12) were described by a linear trend line. In all trend line the correlation coefficient R^2 between flow rate and rotational speed is close to one. A very high value of the correlation coefficient R^2 is an effect of maintaining very precise parameters during the tests (described in Section 6.2). Furthermore the use of piston flow meter also contributed to the small scatter of the measurement results (the piston flow meter measured the average flow rate corresponding to more than 18 revolutions of the motor shaft). Thus, the results of the experimental research confirm the theoretical consideration and the flow rate in a hydraulic motor can be described by a linear function of rotational speed of a motor.

The value of the geometric working volume q_g of the motor ($34.44 \text{ cm}^3/\text{rev}$) is greater than the theoretical working volume q_t ($32.5595 \text{ cm}^3/\text{rev}$ —calculated according to the proposed new method) by $1.8805 \text{ cm}^3/\text{rev}$. That is, the q_g is as much as 5.5% larger than the q_t calculated according to the new method. The main reason of the difference between the q_t and q_g is technology of manufacturing of working mechanism elements. These elements are electrically cutting with wire with a certain allowance for finishing treatment (lapping). In this way, the q_g is definitely smaller than q_t .

The results of the experimental research confirm that:

- It is possible to determine the pressure drop Δp_{ich} in internal channels and to calculate the pressure drop Δp_i in working chambers;
- the effective absorbency q_e is a linear function of Δp_i and non-linear function of the inverse of rotational speed n of the motor (formula (51) and Figure 15);
- the rotational speed n of a hydraulic motor has no influence on the theoretical working volume q_t ;
- the actual working volume q_r is a third order polynomial function of pressure drop Δp_i in working chambers of the motor (Figure 16). That is, Formula (45) is true. In the tested satellite motor is:

$$q_r = \underbrace{32.5595}_{q_t} + \underbrace{0.179759 \cdot \Delta p_i - 0.0071783 \cdot \Delta p_i^2 + 0.0001009 \cdot \Delta p_i^3}_{\Delta q_g} \quad (59)$$

Furthermore it has been shown that is possible to determine the q_r and q_t including the influence of oil compressibility β .

The results of the experimental research show some difference (about 2.2%) in the theoretical working volume q_t calculated using the new method ($q_t = 32.5595 \text{ cm}^3/\text{rev.}$) and calculated using Balawender's method ($q_t = 33.312 \text{ cm}^3/\text{rev.}$). As the final result of the theoretical working volume should be adopted $q_t = 32.5595 \text{ cm}^3/\text{rev.}$ calculated according to the proposed new method. This decision can be justified by the fact that the Balawender method is a simplified method (adopted simplification: $\Delta p_i \approx \Delta p$, linear relationship between q_e and $1/n$ (Figure 13) and linear relationship between D and Δp (Figure 14)). For users of hydraulic motor, the difference of 2.2% is not large and is usually imperceptible. However, for researchers of positive displacement machines, this difference can be significant because it directly influences on assessment of energetic losses in the motor.

Due to the fact the working volume increases under the pressure (Figure 16), the values of q_r according to Formula (45) should be taken into account to calculate the volumetric and mechanical losses in a hydraulic motor.

In the publicly available literature, the volumetric efficiency in a hydraulic motor is defined as:

$$\eta_v = \frac{q_t \cdot n}{q_t \cdot n + Q_L} \quad (60)$$

For theoretical working volume calculated according to a simplified Balawender's method, the volumetric efficiency η_v of the motor for $\Delta p < 2 \text{ MPa}$ (calculated according to the above formula) is larger than one ($\eta_v > 1$) (Figure 17). It has no physical sense, of course.

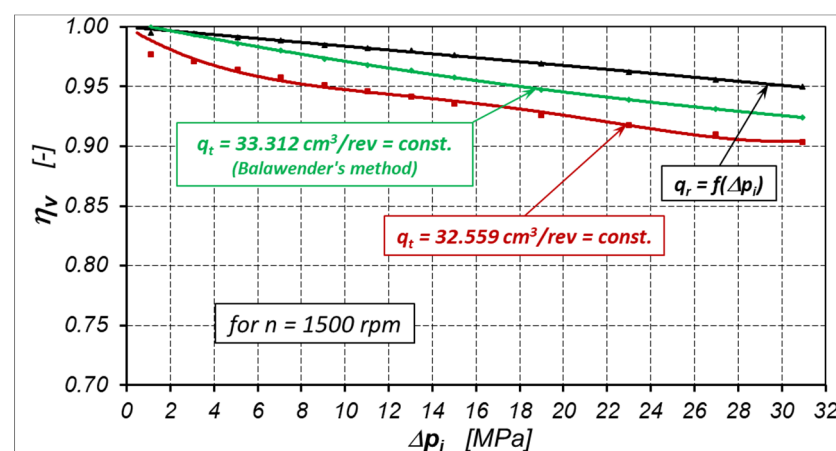


Figure 17. Volumetric efficiency $\eta_v = f(\Delta p_i)$ of satellite motor at $n = 1500 \text{ rpm}$ for q_r and q_t calculated according to the Balawender's method and the new method.

The theoretical working volume q_t in all range of pressure drop Δp in a motor is adopted for calculation of losses in this motor and its efficiencies. In this way:

- The volumetric losses are overestimated;
- the mechanical losses are underestimated;
- the volumetric efficiency η_v is underestimated (Figure 17);
- the mechanical efficiency η_m is overestimated.

In the context of the aforementioned theoretical q_t and actual working volume q_r , instead of the theoretical flow rate Q_t in a hydraulic motor, the actual flow rate Q_r should be used, defined as:

$$Q_r = q_r \cdot n \quad (61)$$

where for $\Delta p_i = 0$ is $q_r = q_t$ and $Q_r = Q_t$. Whereas the volumetric efficiency for any Δp_i is:

$$\eta_v = \frac{q_r \cdot n}{q_r \cdot n + \Delta q_L \cdot n + Q_{Lfg} + Q_C + Q_{Le}} \quad (62)$$

An example of the volumetric efficiency characteristics of the satellite motor for $n = 1500$ rpm, calculated according to Formulas (60) and (62), is shown in Figure 17.

Thus, it is necessary to take the actual working volume q_r (as a function of pressure drop Δp_i in working chambers) to calculate the losses in the hydraulic motor.

8. Summary

The above article presents a new methodology for determining the theoretical q_t and actual q_r working volume of a hydraulic motor. The proposed new method takes into account the pressure drop Δp_{ich} in the motor's internal channels and the liquid compressibility (the location of the flow meter in the measurement system). The actual working volume q_r is a non-linear function of the pressure drop Δp_i in the working chambers. Therefore, the actual working volume q_r should be taken to calculate the volumetric and mechanical losses, and also the volumetric and mechanical efficiency of the motor. In the tested satellite motor, the q_r is changing about 3% in all range of Δp_i . Is it a lot or a little? It is difficult to assess. Therefore, in order to be convinced of this, a satellite motor with a greater stiffness of the working mechanism should be built. The greater stiffness of the working mechanism is possible to obtain in two ways (separately or together):

- Mainly by increasing the diameter of the bypass,
- by changing the construction of the teeth in working mechanism elements.

The geometrical working volume of a satellite motor is definitely bigger than the theoretical working volume (about 5.5%). To explain this difference, it would be worthwhile to test the motor with reduced tip clearances and backlash clearances in the satellite mechanism. In this way, it will reduce the volume between the mating teeth of the satellite mechanism. This volume also has an impact on the process of pumping liquid through the working mechanism. The smaller this volume, the smaller the volumetric losses? The smaller an influence of rotational speed on the volumetric losses in a hydraulic motor? This thesis would require proof.

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