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# The complexity of the *T*-coloring problem for graphs with small degree

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## Abstract

In the paper we consider a generalized vertex coloring model, namely *T*-coloring. For a given finite set *T* of nonnegative integers including 0, a proper vertex coloring is called a *T*-coloring if the distance of the colors of adjacent vertices is not an element of *T*. This problem is a generalization of the classic vertex coloring and appeared as a model of the frequency assignment problem. We present new results concerning the complexity of *T*-coloring with the smallest span on graphs with small degree  $\Delta$ . We distinguish between the cases that appear to be polynomial or NP-complete. More specifically, we show that our problem is polynomial on graphs with  $\Delta \leq 2$  and in the case of *k*-regular graphs it becomes NP-hard even for every fixed *T* and every k > 3. Also, the case of graphs with  $\Delta = 3$  is under consideration. Our results are based on the complexity properties of the homomorphism of graphs. © 2003 Published by Elsevier B.V.

Keywords: Vertex coloring; T-coloring; T-span; Homomorphism; NP-completeness

#### 1. Introduction

We consider the *T*-coloring problem, as a generalized classical vertex coloring problem, which is one of the variants of the channel assignment problem in broadcast networks [8,16]. In this problem one wishes to assign to each transmitter  $x_i \in \{x_1, \ldots, x_n\}$ , located in a region, a frequency  $f(x_i)$  avoiding interference between transmitters, i.e.

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<sup>&</sup>lt;sup>1</sup> Supported by FNP.

two interfering transmitters (because of proximity, meteorological or other reasons) must be assigned frequencies so that the distance between them does not belong to the forbidden set T of nonnegative integers including 0. The most common objective is to minimize the span of a frequency band. For more about applications of this problem the reader is referred to [2,3,14,15].

Let G = (V, E) be a simple loopless graph with vertex set V = V(G) and edge set E = E(G). By  $\Delta(G)$  we mean the maximum degree  $\rho(v)$  over all vertices v of graph G, by  $\chi(G)$  and  $\omega(G)$  we denote the chromatic number and the clique number of graph G, respectively. Let G(W) denote the subgraph of graph G induced by  $W \subset V$ .

**Definition 1.** Let *T* be a finite set of nonnegative integers satisfying  $0 \in T$ . By a *T*-coloring of graph *G* we mean a vertex coloring  $c: V \to \mathbb{N}$  satisfying  $|c(v) - c(w)| \notin T$ , whenever  $\{v, w\} \in E$ . The *T*-span is defined as  $\operatorname{sp}_T(G) = \min_c \operatorname{sp}_T(G, c)$ , where  $\operatorname{sp}_T(G, c) = \max c(V) - \min c(V)$  and *c* is a proper vertex *T*-coloring of graph *G*. A *T*-coloring *c* is said to be optimal if  $\operatorname{sp}_T(G, c) = \operatorname{sp}_T(G)$ .

Following [13] we introduce the notion of T-graphs.

**Definition 2.** For a given set T, we define an infinite T-graph  $G_T$ , with vertex set  $V(G_T) = \mathbb{N} \cup \{0\}$  and edge set  $E(G_T) = \{\{x, y\} : |x - y| \notin T\}$ . By  $G_T^{d+1}$  we mean the subgraph of  $G_T$  induced by  $\{0, \ldots, d\}$ .

Given a graph G, set T and positive integer k, the problem of verifying the inequality  $\operatorname{sp}_{T}(G) \leq k$  we call the T-Span Problem. This differs from the T-Coloring Problem, which requires an optimal T-coloring as its output. The notion of a T-coloring was introduced in [8]. The problem has been studied extensively (see [3,4,12,13-18]). The majority of results concern lower and upper bounds on  $sp_{\tau}(G)$ , see [3,11,17]. The first complexity result comes independently from [6,12], where the authors showed NP-completeness in the strong sense of the T-Span Problem on complete graphs (so even a pseudopolynomial algorithm for the T-Span Problem cannot exist unless P=NP). We call the above problems FIXED T-SPAN PROBLEM and FIXED T-COLORING PROBLEM if set T is fixed. Furthermore, in [7] the authors have developed a linear algorithm for solving the FIXED T-COLORING PROBLEM on complete graphs (but exponential with respect to  $\max T$ ). So far, the problem on graphs with "small" degree has been still open. Therefore, in Sections 2 and 3 we deal with some new properties of homomorphisms and in Section 5 we show NP-completeness of the FIXED T-SPAN PROBLEM on subcubic graphs (i.e. with  $\Delta \leq 3$ ), and r-regular graphs (i.e. with all vertices of degree r) with  $r \ge 3$ . In Section 4 we show a polynomial time algorithm for the T-COLORING PROBLEM on graphs with  $\Delta \leq 2$ .

## 2. Simple properties of graph homomorphisms

The idea of graph homomorphism is a generalization of vertex coloring. Moreover, it generalizes the T-coloring problem as well.

**Definition 3.** For two simple graphs G and H a graph homomorphism is a function  $h: V(G) \to V(H)$  such that  $\{h(v), h(w)\} \in E(H)$ , whenever,  $\{v, w\} \in E(G)$  for all  $v, w \in V(G)$ .

We write  $G \to H$  if there exists a homomorphism from G to H. Furthermore, if the homomorphism is onto, then it is called an *epimorphism*. In addition, if there exists  $h^{-1}$  and it is a homomorphism from H to G, then we call it an *isomorphism* and graphs G and H are said to be isomorphic, in symbols  $G \simeq H$ . We write  $H \subset G$  if H is isomorphic to any subgraph of G.

There is a straightforward equivalence between the properties of *T*-span and the existence of homomorphism from *G* to  $G_T^{d+1}$  (see [13]).

**Proposition 4.** Given a graph G, any set T and a nonnegative integer d we have  $sp_T(G) \leq d$  if and only if  $G \to G_T^{d+1}$ .

Let us note that if  $T = \{0\}$ , then the *T*-coloring problem reduces to the well-known vertex coloring problem, and moreover  $G_T^{d+1} \simeq K_{d+1}$ . Thus we get

**Corollary 5.** Given a graph G and a positive integer d we have  $\chi(G) \leq d$  if and only if  $G \to K_d$ .

The composition of graph homomorphisms is still a graph homomorphism. Moreover, an image of a complete graph under a homomorphism is a complete graph with the same number of vertices so

**Corollary 6.** If  $K_n \to G$  then  $K_n \in G$ .

And

**Proposition 7.** If  $h: V(G) \to V(H)$  is a homomorphism then  $\psi(G) \leq \psi(H(h(V(G))))$ , where  $\psi$  is any of the functions from the list  $\{\chi, \omega, \operatorname{sp}_T\}$ .

From the above is easy to see that if  $G \to H$  and H is bipartite, then graph G is bipartite. Concluding this section note an important upper bound proved in [17].

**Theorem 8** (Tesman [17]). For any given graph G and set T the following inequality holds

 $\operatorname{sp}_T(G) \leq |T| \cdot (\chi(G) - 1).$ 

Let us also recall that

**Theorem 9** (Brooks). If G is a connected graph that is neither a complete graph nor an odd cycle, then  $\chi(G) \leq \Delta(G)$ .

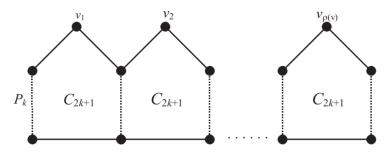


Fig. 1. Graph  $A_v^k$  replacing the vertex v.

## 3. Homomorphisms into odd cycles

The problem of graph homomorphism is considered in [1,5]. Let H be a fixed graph, the decision problem of the existence of a homomorphism from G to H will be denoted Hom(H), where G is any graph from the specified family. The most important result comes from [9].

**Theorem 10** (Hell and Nesetril [9]). The problem Hom(H) on arbitrary graphs is polynomial, whenever H is bipartite, otherwise it is NP-complete.

In this section we prove that the problem  $\text{Hom}(C_{2k+1})$  on subcubic graphs is NPcomplete for every positive integer  $k \ge 2$ , in contrast to the problem  $\text{Hom}(C_3)$ , which is polynomial. Moreover, we prove analogous result for 3-regular graphs and NPcompleteness of the problem  $\text{Hom}(C_{2k+1})$  on *r*-regular graphs, for every  $r \ge 4$  and  $k \ge 1$ .

We start with a general construction. Let G be an arbitrary graph and k be any positive integer greater than 1. We replace each vertex  $v \in V(G)$  of degree  $\rho(v)$  with the graph  $A_v^k$  shown in Fig. 1 (the dotted vertical lines in Fig. 1 mean path  $P_k$ ). We replace also every edge  $\{v, w\} \in E(G)$  with the edge  $\{v_i, w_j\}$  such that no two inserted edges are incident. Let  $G'_k$  be the graph constructed from G as above. It is easy to see that  $G'_k$  is always a subcubic graph.

**Theorem 11.** The problem Hom( $C_{2k+1}$ ),  $k \ge 2$  is NP-complete on subcubic graphs.

**Proof.** By Theorem 10 it suffices to show  $G \to C_{2k+1}$  iff  $G'_k \to C_{2k+1}$ . First, observe that  $A_v^k \to C_{2k+1}$  and moreover for every homomorphism  $h_v: V(A_v^k) \to V(C_{2k+1})$  we have  $|h_v(\{v_1, \ldots, v_{\rho(v)}\})| = 1$ . Otherwise, we have  $h_v(v_i) \neq h_v(v_{i+1})$  for some  $i \in \{1, \ldots, \rho(v) - 1\}$ , hence  $h_v(v_i) = h_v(x)$ , where  $\{v_i, s\}, \{v_{i+1}, s\}, \{s, x\} \in E(A_v^k)$  and  $x \notin \{v_1, \ldots, v_{\rho(v)}\}$ . Thus  $C_{2l-1}$  is subgraph of  $C_{2k+1}(h(V(A_v^k)))$  for some l < k, which is impossible. So, constructing a homomorphism  $g: V(G) \to V(C_{2k+1})$  from a homomorphism  $g': V(G'_k) \to V(C_{2k+1})$  is straightforward.

Conversely, let  $g: V(G) \to V(C_{2k+1})$  be a homomorphism, then we let  $g'(v_i) = g(v)$ and for  $w \in V(A_v^k) \setminus \{v_1, \dots, v_{\rho(v)}\}$   $g'(w) = \tau_v \circ h_v(w)$ , where  $h_v: V(A_v^k) \to V(C_{2k+1})$  is a

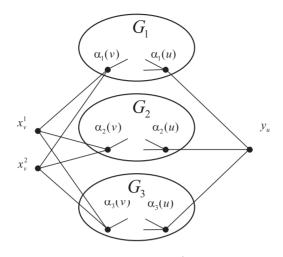


Fig. 2. A graph G'.

homomorphism and  $\tau_v$  is any automorphism of  $C_{2k+1}$  such that  $\tau_v(h_v(v_i)) = g(v)$ . One can check that  $g': V(G'_k) \to V(C_{2k+1})$  is a homomorphism.  $\Box$ 

**Theorem 12.** The problem Hom $(C_{2k+1})$ ,  $k \ge 2$  is NP-complete on 3-regular graphs.

**Proof.** It suffices to show the equivalence  $G \to C_{2k+1}$  iff  $G' \to C_{2k+1}$  for any subcubic connected graph G, where  $k \ge 2$  and G' is a cubic graph defined as follows. Let  $\alpha_i$  be an isomorphism from graph G to its *i*th isomorphic copy  $G_i$ , for i = 1, 2, 3, which are vertex disjoint. Let  $V_j \subset V(G)$  be the set of vertices of degree j. We define  $V(G') = \bigcup_{i=1}^3 V(G_i) \cup \bigcup_{v \in V_1} \{x_v^1, x_v^2\} \cup \bigcup_{u \in V_2} \{y_u\}$  and  $E(G') = \bigcup_{i=1}^3 E(G_i) \cup$  $\bigcup_{v \in V_1} \bigcup_{i=1}^3 \{\{x_v^1, \alpha_i(v)\}, \{x_v^2, \alpha_i(v)\}\} \cup \bigcup_{u \in V_2} \bigcup_{i=1}^3 \{\{y_u, \alpha_i(u)\}\}$  (see Fig. 2). Assuming that  $x_v^j$  and  $y_u$  are different vertices for j = 1, 2 and  $v, u \in V(G)$ , it is obvious that G'is a cubic graph.

Now, suppose  $g: V(G) \to V(C_{2k+1})$  is a homomorphism. Let  $g': V(G') \to V(C_{2k+1})$ be defined g'(w) = g(v) for  $w \in \{\alpha_1(v), \alpha_2(v), \alpha_3(v)\}$  and  $v \in V(G)$ ,  $g'(x_v^i) = g(z)$  for  $\{z, v\} \in E(G), g'(y_v) = g(z)$  for any z adjacent to v. Thus g' is a well-defined homomorphism. Conversely, if g' is a homomorphism from G' to  $C_{2k+1}$  then  $g = g' \circ \alpha_1$  is a homomorphism from G to  $C_{2k+1}$ .  $\Box$ 

**Theorem 13.** The problem  $Hom(C_{2k+1})$  is NP-complete on r-regular graphs for every fixed integer  $k \ge 1$  and  $r \ge 4$ .

**Proof.** By induction on  $r \ge 4$ , consider r + 1 isomorphic copies of any r regular graph. Using the analogous method as that in Theorem 12 we can show that the problem Hom $(C_{2k+1})$  is NP-complete for any  $k \ge 2$  and for all  $r \ge 4$ . In [10] the author proved NP-completeness of edge 3-chromaticity of 3-regular graphs. Since line

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graphs of 3-regular graphs are 4-regular, the problem of 3-chromaticity of 4-regular graphs is NP-complete. The construction from Theorem 12 is carried over to the case  $H_{Om}(C_3)$  on *r*-regular graphs with  $r \ge 4$ .  $\Box$ 

## 4. Polynomial algorithm for cycles

We show a polynomial-time algorithm for graphs with  $\Delta \leq 2$ .

**Theorem 14.** The T-COLORING PROBLEM on graphs with degree not exceeding 2 can be solved in time  $O(n|T|^2 \log |T|)$ .

**Proof.** Bipartite graphs can be optimally colored with 1 and min  $\mathbb{N} \setminus T + 1$ , thus all we need is considering odd cycles. Let *T* be any set and *a* be an arbitrary integer. We ask if  $\operatorname{sp}_T(C_{2k+1}) \leq a-1$ . By Theorem 8 we have  $\operatorname{sp}_T(C_{2k+1}) \leq 2|T|$ . Thus using the standard bisection method we need only check  $1 + \log_2|T|$  inequalities to find  $\operatorname{sp}_T(C_{2k+1})$ .

In the following, we sketch the idea of the algorithm. Let  $TAB(v_i)[1...a]$  be a table of logical values associated with vertex  $v_i$  and defined as follows:  $TAB(v_i)[j] = TRUE$ if and only if there exists a *T*-coloring of path  $v_1, ..., v_i$  using colors not greater than *a* such that  $v_1$  is colored with 1 and  $v_i$  is colored with *j*. So,  $TAB(v_1)$  has value TRUE only on its first position and  $TAB(v_{i+1})[y] = TRUE$  if and only if there exists  $z \in \{1, ..., a\}$  such that  $|z - y| \notin T$  and  $TAB(v_i)[z] = TRUE$ . We see that there exists a *T*-coloring iff  $TAB(v_{2k+1})[j] = TRUE$  for some  $j - 1 \notin T$ , so constructing the *T*-coloring is straightforward. It is obvious that the complexity of the above algorithm is  $O(k|T|^2 \log|T|)$ .  $\Box$ 

#### 5. Main results

Based on Theorem 11 we can prove the main result of this paper. Before doing this, we introduce the following notion.

**Definition 15.** For a given set T, by  $d_T$  we mean the number such that  $G_T^{d_T}$  is bipartite and  $G_T^{d_T+1}$  is not bipartite.

**Lemma 16.** For any set T the following inequality holds:

 $d_T \leq \operatorname{sp}_T(K_3)$ 

and, moreover,  $d_T$  can be determined in polynomial time.

**Proof.** Let us notice that  $\chi(G_T^{d_T+1}) = \chi(G_T^{d_T}) + 1 = 3$ . Thus from Corollary 5 it follows  $G_T^{d_T+1} \to K_3$ , hence by Proposition 7  $\operatorname{sp}_T(G_T^{d_T+1}) \leq \operatorname{sp}_T(K_3)$ . By Proposition 4  $\operatorname{sp}_T(G_T^{d_T+1}) \leq d_T$ . Assuming  $\operatorname{sp}_T(G_T^{d_T+1}) \leq d_T - 1$  we get at once  $G_T^{d_T+1} \to G_T^{d_T}$  but this contradicts the definition of  $d_T$ . So, we get  $d_T = \operatorname{sp}_T(G_T^{d_T+1}) \leq \operatorname{sp}_T(K_3)$ . By

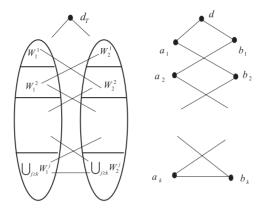


Fig. 3. A graph  $G_T^{d_T+1}$  (left) and a cycle  $C_{2k+1}$  (right).

Theorem 8 sp<sub>T</sub>(K<sub>3</sub>)  $\leq 2|T|$ , hence using the bisection method we can determine the greatest  $d_T$  such that  $G_T^{d_T}$  is bipartite. This can be done in time O( $|T|^2 \log |T|$ ).  $\Box$ 

**Lemma 17.** Given any set T, we have  $d_T = \operatorname{sp}_T(K_3)$  if and only if  $K_3 \subset G_T^{d_T+1}$ .

**Proof.** By Corollary 6  $K_3 \in G_T^{d_T+1}$  is equivalent to  $K_3 \to G_T^{d_T+1}$ . Assume  $K_3 \in G_T^{d_T+1}$ , then by Proposition 4 sp<sub>T</sub>( $K_3$ )  $\leq d_T$ , hence from Lemma 16 it follows that  $d_T = \text{sp}_T(K_3)$ . The converse implication is straightforward by Proposition 4.  $\Box$ 

Let us denote by  $C_T$  the shortest odd-length cycle in graph  $G_T^{d_T+1}$ .

**Lemma 18.** There exists a homomorphism  $h: V(G_T^{d_T+1}) \to V(C_T)$ .

**Proof.** We only have to construct a homomorphism on the vertices of the connected component of  $G_T^{d_T+1}$  containing vertex  $d_T$ , because the other components are bipartite. So let  $V_1$  and  $V_2$  be a bipartition of a bipartite graph obtained from this component by removing  $d_T$  and let  $W_i^j$ , i = 1, 2 and  $j \ge 1$ , be the vertex subset of  $V_i$  of distance j from vertex  $d_T$  in the graph  $G_T^{d_T+1}$ . Finally, let  $W_1^0 = W_2^0 = \{d_T\}$ . Let  $C_{2k+1} = (\{d, a_1, b_1, \dots, a_k, b_k\}, \{\{d, a_1\}, \{d, b_1\}, \{a_1, b_2\}, \{b_1, a_2\}, \dots, \{a_{k-1}, b_k\}, \{b_{k-1}, a_k\}, \{a_k, b_k\}\})$  be any cycle isomorphic to  $C_T$ . Let us define  $h(d_T) = d$ ,  $h(W_1^j) = \{a_j\}$  and  $h(W_2^j) = \{b_j\}$  for  $j = 1, \dots, k$  and  $h(W_i^j) = h(W_i^k)$  for j > k, i = 1, 2 (see Fig. 3).

The construction of *h* is correct because any vertex from  $W_i^j$ , j > 0, can have neighbours only in the sets  $W_{3-i}^{j\pm 1}$  and  $W_{3-i}^j$ , and the latter case is impossible for j < k.  $\Box$ 

**Lemma 19.** For any graph G the following equivalence holds:  $G \to G_T^{d_T+1}$  if and only if  $G \to C_T$ .

**Proof.** Let  $G \to G_T^{d_T+1}$ , hence from Lemma 18 it follows  $G \to C_T$ . Conversely, assume that  $G \to C_T$ . By definition  $C_T \tilde{\subset} G_T^{d_T+1}$ , thus we get  $G \to G_T^{d_T+1}$ .  $\Box$ 

**Theorem 20.** The T-SPAN PROBLEM can be solved in polynomial time on subcubic graphs for all sets T satisfying  $K_3 \tilde{\subset} G_T^{d_T+1}$ . The FIXED T-SPAN PROBLEM is NP-complete on cubic graphs for all sets T not satisfying  $K_3 \tilde{\subset} G_T^{d_T+1}$ .

**Proof.** Let *T* be a fixed set and *k* be any positive integer. By Theorem 8 the case  $G = K_4$  is polynomial and can be solved in  $O(|T|^3)$  time (by Proposition 4 it reduces to the problem of finding the smallest *d* such that  $K_4 \tilde{\subset} G_T^d$ ; by Theorem 8  $K_4 \tilde{\subset} G_T^{3|T|+1}$  and the fact that 0 is a vertex of a maximal clique of  $G_T^d$ , it reduces to searching all the triples of vertices of  $G_T^{3|T|+1}$ ). For any subcubic graph  $G \neq K_4$  we ask if  $\operatorname{sp}_T(G) \leq k$ . Suppose that  $K_3 \tilde{\subset} G_T^{d_T+1}$ . Brooks' theorem implies  $G \to K_3$ , thus by Lemma 17 and

Suppose that  $K_3 \subset G_T^{d_T+1}$ . Brooks' theorem implies  $G \to K_3$ , thus by Lemma 17 and Proposition 7 sp<sub>T</sub>(G)  $\leq d_T$ . According to Proposition 4 we have sp<sub>T</sub>(G)  $< d_T$  iff G is bipartite, hence to solve T-SPAN PROBLEM for graph G we only need to check if G is bipartite (O(n + m) time) and if it is so then sp<sub>T</sub>(G) equals the smallest positive integer not belonging to T (which we can find in O(|T|) time). Otherwise, sp<sub>T</sub>(G)= $d_T$ , computable in time O( $|T|^2 \log |T|$ ).

Now assume that  $K_3$  is not isomorphic to any subgraph of  $G_T^{d_T+1}$  and let  $k=d_T$ . From Proposition 4 we have  $\operatorname{sp}_T(G) \leq k$  iff  $G \to G_T^{d_T+1}$ . By Lemma 19 we get  $\operatorname{sp}_T(G) \leq k$ iff  $G \to C_T$  and, moreover,  $C_T$  is an odd cycle of length greater than 4. By Theorem 12 the problem Hom $(C_T)$  on cubic graphs is NP-complete and so is the FIXED *T*-SPAN PROBLEM.  $\Box$ 

**Corollary 21.** The T-SPAN PROBLEM is NP-complete in the strong sense on 3-regular graphs.

**Proof.** By Theorem 20 and Lemma 17 it suffices to verify that for  $T = \{0, 2, 3\}$  we have  $d_T = 4 < \operatorname{sp}_T(K_3) = 5$ .  $\Box$ 

It is worth observing that if for some set T we put  $k = d_T$ , then by Lemma 19 for any graph G the question if  $\operatorname{sp}_T(G) \leq k$  is equivalent to  $G \to C_T$ . So, if for every  $k \geq 1$  the problem  $\operatorname{Hom}(C_{2k+1})$  is NP-complete on a class  $\mathscr{G}$ , then the FIXED T-SPAN PROBLEM on the class  $\mathscr{G}$  is NP-complete as well. Thus from Theorem 13 we have the following:

**Theorem 22.** For every set T and integer  $r \ge 4$  the FIXED T-SPAN PROBLEM is NPcomplete on r-regular graphs.

**Corollary 23.** The T-SPAN PROBLEM is NP-complete in the strong sense on r-regular graphs for any  $r \ge 3$ .

Table 1 Now we sum up all the above results in the following table. Recall that the numbers appearing in the third column are polynomially computable functions of T.

Table 1

The complexity of the T-SPAN PROBLEM and T-COLORING PROBLEM on graphs with bounded degree

| Graph   | Problem  | Property of T  | Complexity                                       | Reference  |
|---|--|--|--|--|
| $ \frac{\Delta \leq 2}{\Delta \leq 3} $ 3-regular<br><i>r</i> -regular,<br>$r \geq 4$ | T-COLORING PROBLEM<br>T-COLORING PROBLEM<br>FIXED T-SPAN PROBLEM<br>FIXED T-SPAN PROBLEM | any<br>$\omega(G_T^{d_T+1}) \ge 3$ $\omega(G_T^{d_T+1}) \le 2$ any | $O(n T ^2 \log T )$ $O(n^2 +  T ^3)$ $NPC$ $NPC$ | Theorem 14<br>Theorem 20<br>Theorem 20<br>Theorem 22 |

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